

# Radiation Hydrodynamics with High-Order Finite Elements in the BLAST Code

MultiMat 2017, Santa Fe

Vladimir Tomov

R. Anderson, T. Brunner, V. Dobrev, Tz. Kolev, and R. Rieben

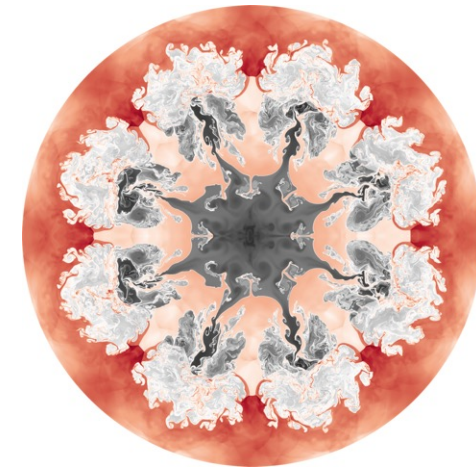
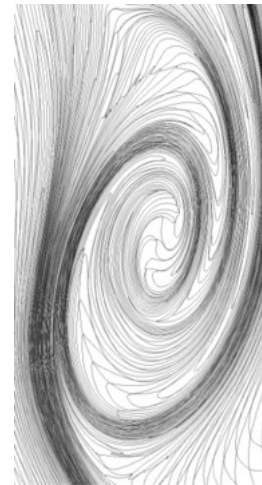
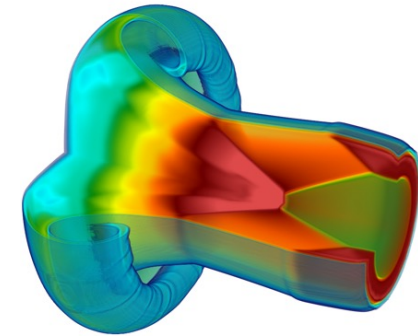
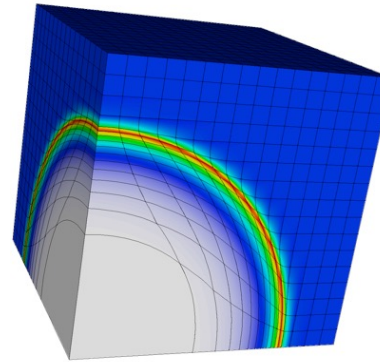
September 20, 2017



# BLAST is a high-order finite element ALE code

We solve the Euler equations by a Lagrange + remap method

- Multi-material support for general EOS, strength and elasto-plastic flow models.
- Support for 2Dxy, 2Drz and 3D curved tri/tet/quad/hex meshes.
- Robustness and symmetry, reduction of mesh imprinting.
- High-order convergence on smooth tests for the full ALE algorithm.
- FLOP-intensive numerical kernels.
- Coupled to single-group rad-diffusion, MHD coupling is in progress.



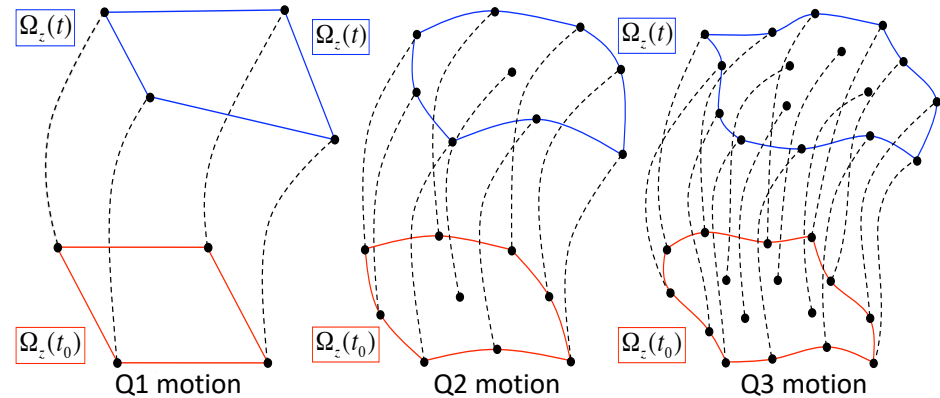
# Multi-material Lagrangian phase overview

Sub-zonal resolution by combining  $H^1$ ,  $L_2$ , and point-wise quantities

$$\frac{d\eta_k}{dt} = \alpha_k, \quad \frac{d(\eta_k \rho_k)}{dt} = -\eta_k \rho_k \nabla \cdot v$$

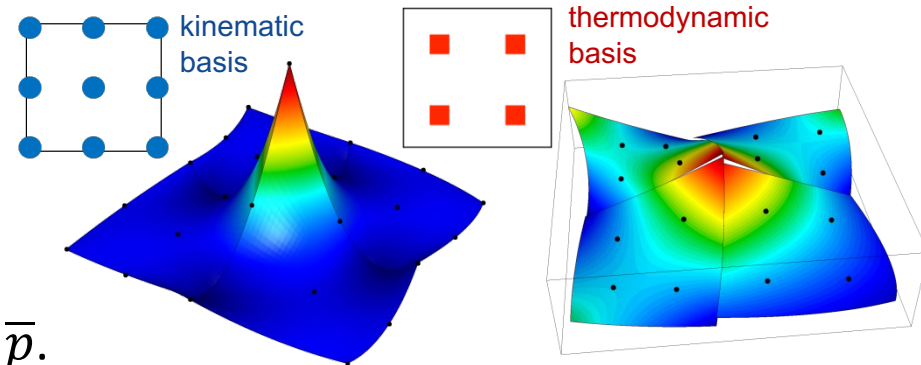
$$\frac{dx}{dt} = v, \quad \sum_k \eta_k \rho_k \frac{dv}{dt} = \nabla \cdot \sum_k \eta_k \sigma_k$$

$$\eta_k \rho_k \frac{de_k}{dt} = \eta_k \sigma_k : \nabla v - \alpha_k \bar{p}$$



*Curvilinear zones represent material flow better*

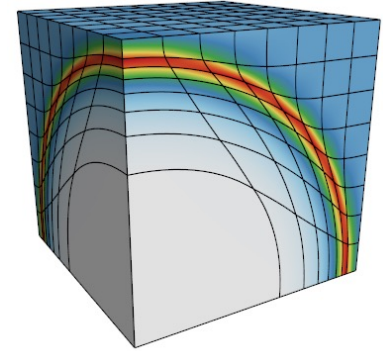
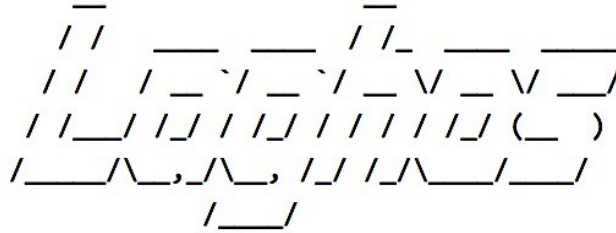
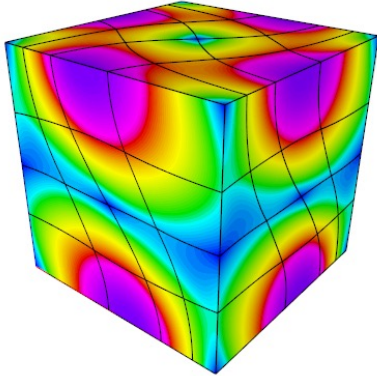
- Continuous HO kinematics for position  $x$ , velocity  $v$ .
- Discontinuous HO thermodynamics for specific internal energies  $e_k$ .
- Point-wise closure computations for volume fractions  $\eta_k$ , increments  $\alpha_k$  and  $\bar{p}$ .
- Point-wise mass conservation for densities  $\rho_k$ .



*High-order fields lead to sub-zonal resolution*

# LAGHOS: LAGrangian High-Order Solver

Laghos is a new MFEM miniapp for high order hydrodynamics



- Public GitHub website: <https://github.com/CEED/Laghos>
  - Email list: [laghos@llnl.gov](mailto:laghos@llnl.gov)
- Resembles the single material Lagrangian phase of BLAST.
- Supports full assembly and partial assembly options.
- Supports 2D and 3D unstructured meshes - quads / hexes, triangles / tets.
- C++ code with domain-decomposed MPI parallelism.
- Optional in-situ visualization with GLVis.

# High-order mesh optimization phase overview

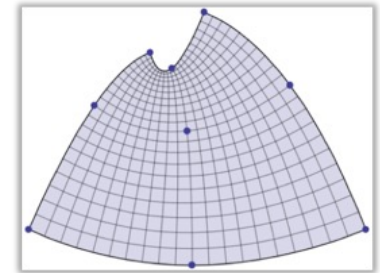
Based on node movement that is controlled by the TMOP paradigm

- We extend the Target-Matrix Optimization Paradigm (TMOP) to high-order meshes.
  - P. Knupp's rigorous theory is used to define high-order mesh quality.
  - Quality metrics are defined with respect to shape / size / alignment.
  - Metrics are computed on quadrature point level.
- We define a global variational minimization problem to find the optimal node positions:

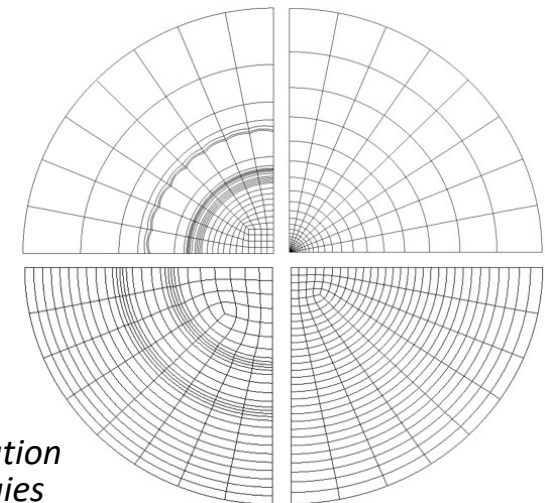
$$F(x) = \sum_K \int_K \mu(x); \quad \frac{\partial F(x)}{\partial x} = 0$$

- Nonlinear solver is applied to the resulting system.
- Capabilities include for compositions of metrics, limited movement, space-time coefficients.

ethos



*Example of a  $Q_2$  zone*



*Example of optimization by different strategies*

# Remap phase overview

Conserved fields are evolved by a sequential FCT algorithm

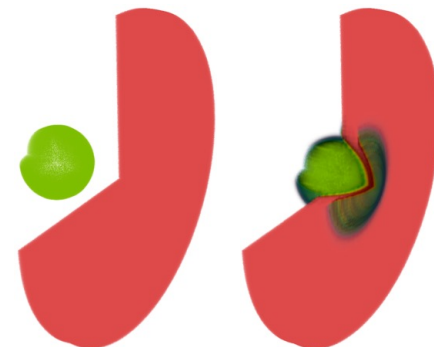
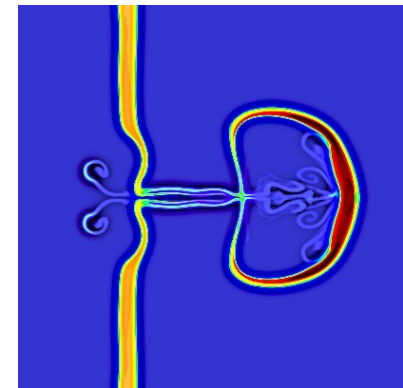
- Formulated as pseudo-time advection.
- We remap (solve for) momentum, volumes, masses, internal energies.
  - Conserved on semi-discrete level.
  - Monotone and conservative transitions to these new variables.
- Bounds are preserved for the primal variables:

$$\eta_{k,i}^{\min} \leq \eta_{k,i}^{n+1} \leq \eta_{k,i}^{\max}, \quad \rho_{k,i}^{\min} \leq \frac{(\eta\rho)_{k,i}^{n+1}}{\eta_{k,i}^{n+1}} \leq \rho_{k,i}^{\max}, \quad e_{k,i}^{\min} \leq \frac{(\eta\rho e)_{k,i}^{n+1}}{(\eta\rho)_{k,i}^{n+1}} \leq e_{k,i}^{\max}$$

- Monotonicity is achieved by a sequential FCT method.
  - Compute  $\eta_k \rightarrow$  compute  $(\eta\rho)_k \rightarrow$  compute  $(\eta\rho e)_k$

$$\frac{dx}{d\tau} = u \quad \frac{d\eta}{d\tau} = u \cdot \nabla \eta$$

$$x(0) = x_0 \quad \eta(x, 0) = \eta_0(x)$$



V. Dobrev, Tz. Kolev, R. Rieben, “High-order curvilinear finite element methods for Lagrangian hydrodynamics”, SIAM J. Sci. Comp., 34(5):604–641, 2012.  
 V. Dobrev, Tz. Kolev, R. Rieben, V. Tomov, “Multi-material closure model for high-order finite element Lagrangian hydrodynamics”, IJNMF, 82(10):689-706, 2016.  
 R. Anderson, V. Dobrev, Tz. Kolev, R. Rieben, V. Tomov, “High-order multi-material ALE hydrodynamics”, Under Review, 2017.

# Coupling to grey radiation diffusion

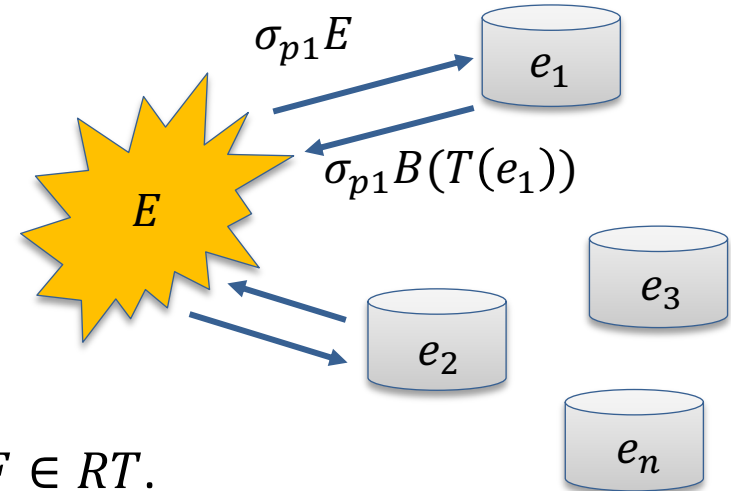
We utilize the  $H(\text{div})$  flux formulation

$$\eta_k \rho_k \frac{\partial e_k}{\partial t} = \eta_k \sigma_k : \nabla v - \alpha_k \bar{p} + \eta_k c \sigma_{p,k} (E - B(T(e_k))),$$

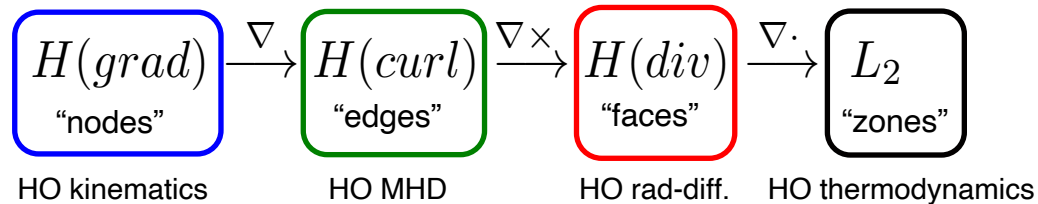
$$\frac{\partial E}{\partial t} + \nabla \cdot F = - \sum_k (\eta_k c \sigma_{p,k} (E - B(T(e_k)))) ,$$

$$\frac{1}{3} \nabla E = - \sum_k \eta_k \frac{\sigma_{r,k}}{c} F ,$$

$$cAE - \mathcal{B}n \cdot F = \mathcal{C} \quad \text{on } \partial\Omega .$$



- Avoiding DG jump terms, we choose  $E \in L_2, F \in RT$ .



- Implicit treatment for  $e_k$  and  $E$ , leading to a non-linear system.
- The hydro terms are explicit, and we lag opacities.
- General EOS and temperature-dependent opacity model for each material.

# Fully-discrete discretization details

The problem is reduced to inverting a Jacobian system

- General implicit time step:  $k = \mathcal{F}(y^n + \Delta tk)$ ;  $k = (\dots, k_{e_k}, \dots, k_E)$

- Semi-discrete system:  $\mathcal{N}(k) = 0$

$$\mathcal{N}(k) = \begin{pmatrix} L_{\rho_k} k_{e_k} + H_k(k_{e_k}) - c\Delta t L_{\sigma_k} k_E - h_k + cL_{\sigma_k} E \\ -\sum_k H_k(k_{e_k}) + Lk_E + c\Delta t \sum_k L_{\sigma_k} k_E + DF - c\sum_k L_{\sigma_k} E \\ \frac{1}{3}\Delta t D^T k_E + \frac{1}{c}R_{\sigma} F + \frac{1}{3}R_n F + \frac{1}{3}b_n - \frac{1}{3}D^T E \end{pmatrix}$$

$L$  matrices are local  $L_2$   
 $R$  matrices are global  $RT$   
 $D$  matrix is transition  $L_2 - RT$   
 $H$  is non-linear operator on  $L_2$

- We use Newton's method to solve the resulting non-linear system:

$$k^n = k^{n-1} - [\partial \mathcal{N}(k^{n-1})]^{-1} \mathcal{N}(k^{n-1})$$

- The Jacobian matrix of the grey diffusion approximation has this form:

$$\partial \mathcal{N}(k) = \begin{bmatrix} \ddots & & & \vdots & \vdots \\ & L_{\rho_k} + \partial H_k & & -c\Delta t L_{\sigma_k} & 0 \\ \mathbf{0} & & \ddots & \vdots & \vdots \\ \dots & -\partial H_k & \dots & L + c\Delta t \sum_k L_{\sigma_k} & D \\ \dots & 0 & \dots & \frac{1}{3}\Delta t D^T & \frac{1}{c}R_{\sigma} + \frac{1}{3}R_n \end{bmatrix}$$

} Material energies  
— Rad energy  
— Rad flux



# Approach #1: inverting the Jacobian matrix

Reduces to a global  $H(\text{div})$  linear system and local  $L_2$  problems

$$\partial \mathcal{N}(k) = \begin{bmatrix} \ddots & & \mathbf{0} & \vdots & \vdots \\ & L_{\rho_k} + \partial H_k & & -c\Delta t L_{\sigma_k} & 0 \\ \mathbf{0} & & \ddots & \vdots & \vdots \\ \dots & -\partial H_k & \dots & L + c\Delta t \sum_k L_{\sigma_k} & D \\ \dots & 0 & \dots & \frac{1}{3}\Delta t D^T & \frac{1}{c}R_\sigma + \frac{1}{3}R_n \end{bmatrix} \begin{array}{l} \text{Material} \\ \text{energies} \\ \text{Rad energy} \\ \text{Rad flux} \end{array}$$

- Approach #1:

- Eliminate the material energy blocks (all  $k_{eK}$ ) and the radiation energy  $k_E$ .
- Solve the global  $H(\text{div})$  linear system to find  $F$ .

Non-symmetric for general space-dependent densities and opacities:

$$\left( \frac{1}{3}\Delta t D^T M_E D + \frac{1}{c}R_\sigma + \frac{1}{3}R_n \right) F = RHS, \quad M_E = L + c\Delta t \sum_k L_{\rho_k} (L_{\rho_k} + \partial H_k)^{-1} L_{\sigma_k}$$

- Back-substitute to find  $k_E$  and each  $k_{eK}$  (by local  $L_2$  inversions).

- We use algebraic hybridization for solving the resulting  $H(\text{div})$  systems.

V. Dobrev, Tz. Kolev, C. S. Lee, V. Tomov, P. Vassilevski, "Algebraic hybridization and static condensation with application to scalable  $H(\text{div})$  preconditioning", Under Review, 2017.

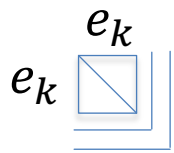
# Approach #2: decomposition to overlapping blocks

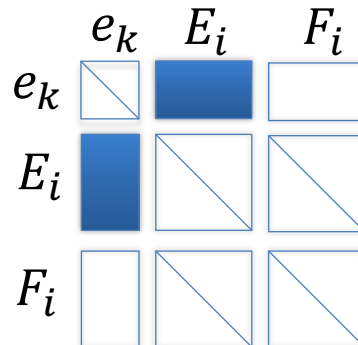
The nonlinear solve resembles a block Gauss-Seidel type iteration

$$\partial \mathcal{N}_{energy}(k) = \begin{bmatrix} \ddots & & \mathbf{0} & \vdots \\ & L_{\rho_k} + \partial H_k & & -c\Delta t L_{\sigma_k} \\ \mathbf{0} & & \ddots & \vdots \\ \dots & -\partial H_k & \dots & L + c\Delta t \sum_k L_{\sigma_k} \end{bmatrix}$$

} Material energies  
— Rad energy

- Approach #2 (originally proposed by P. Nowak):
  - Perform local nonlinear solves in the  $L_2$  blocks (material and rad energies), keeping the rad flux  $F$  explicit.
  - Using the calculated  $k_E$ , solve the global  $H(div)$  linear system.
- More appropriate than approach #1 in the multi-group discretization:

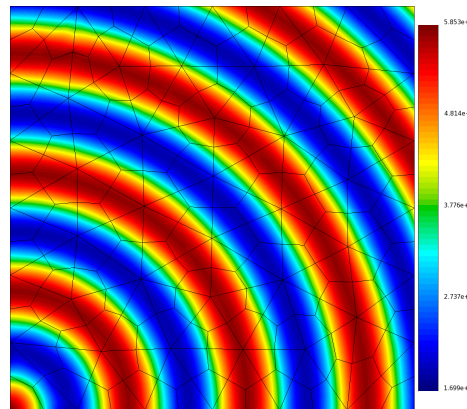
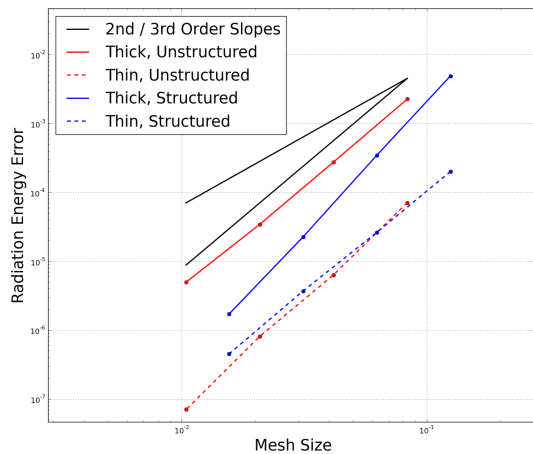

  
 Jacobian structure  
for single group



- Local coupling  $e_k \leftrightarrow E_i$   
(each material to each group).
- Global coupling  $E_i \leftrightarrow F_i$   
(groups are independent).

# Smooth radiation diffusion test / Marshak wave

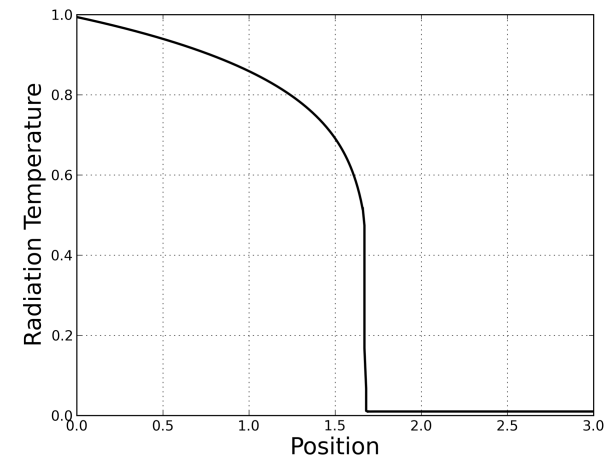
- Convergence on a manufactured smooth problem ( $Q_2/RT_2$  spaces):
  - Designed so that all terms have similar magnitude.



T. Brunner, “Development of a grey nonlinear thermal radiation diffusion Verification problem”, Transactions of the American Nuclear Society, 95:876-878, 2006.

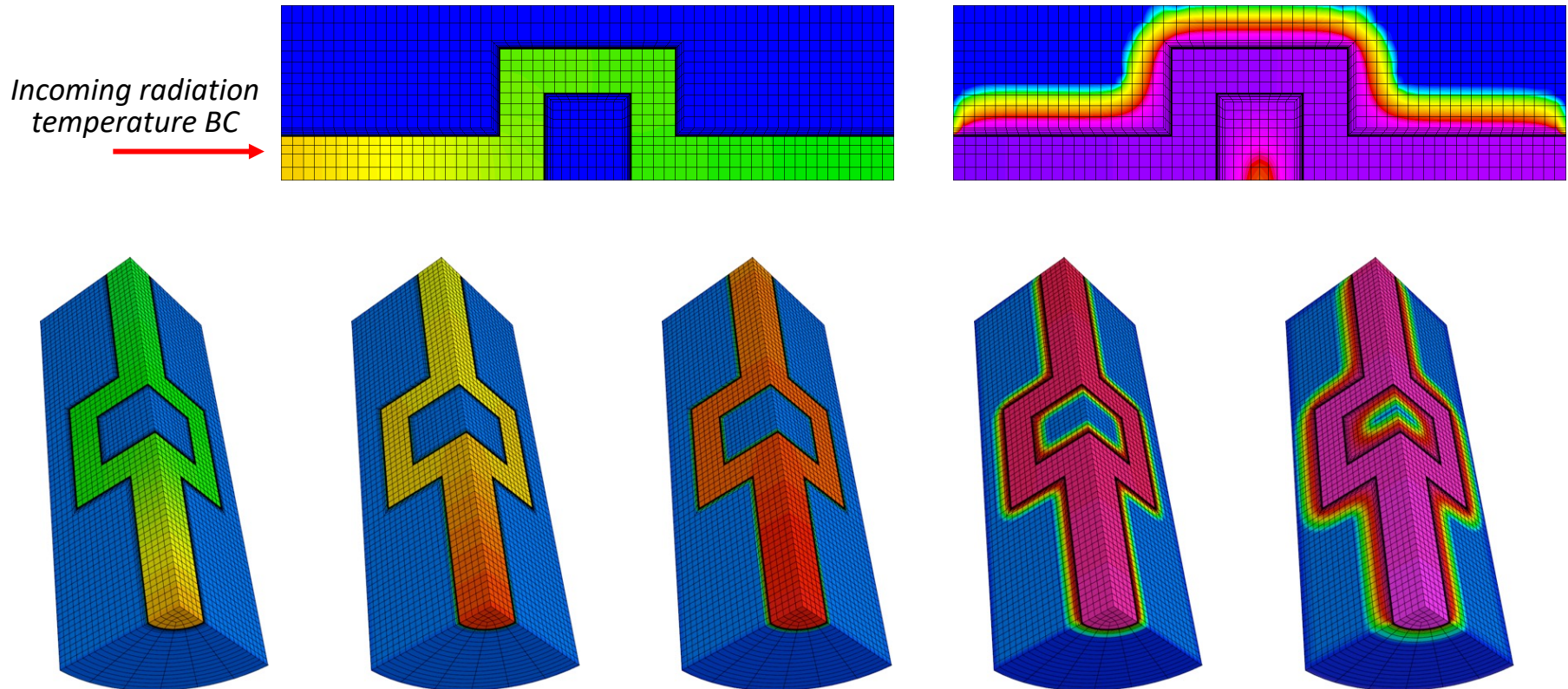
- Simulation of a Marshak-type wave:
  - Opacities are evaluated at a common continuous temperature (a high-order  $H^1$  function).

A. Irvine, I. Boyd, N. Gentile, “Reducing the spatial Discretization error of thermal emission in implicit Monte Carlo simulations”, Journal of Comp. and Theoretical Transport, 45:99-122, 2016.



# The crooked pipe problem in 2Drz and 3D

- Models propagation in a low opacity region ( $\sigma_a = 0.02$ ), surrounded by a thick ( $\sigma_a = 200$ ) region.



# Adding back the material motion

We derive a conservative 2<sup>nd</sup> order IMEX time integrator

- Material motion is altered by scattering of photons:

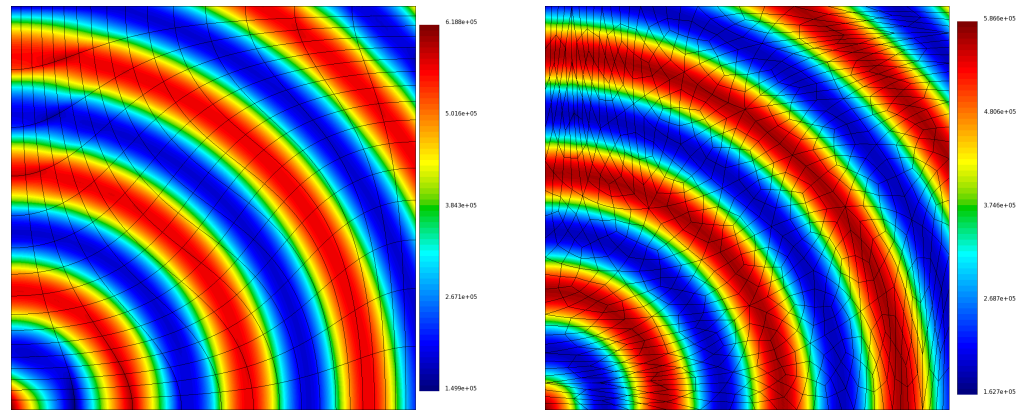
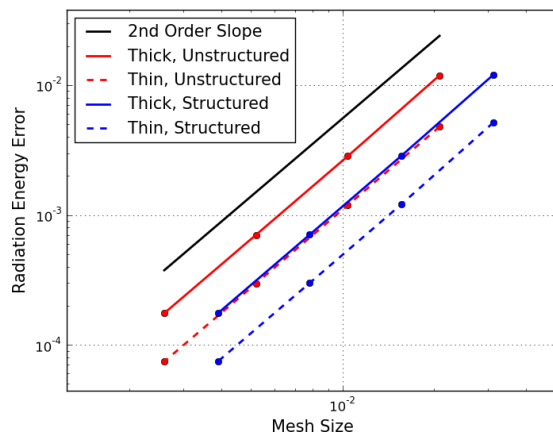
$$\sum_k \eta_k \rho_k \frac{dv}{dt} = \dots + \frac{\sigma_t}{c} F, \quad \frac{dE}{dt} = \dots - \frac{4}{3} E \nabla \cdot v$$

- The new terms are explicit in both equations.
  - Only the RHS of the nonlinear system is affected.
- IMEX time integrator is used to mix the velocity and energy updates.
  - Conservative 2-stage predictor-corrector method.
  - Hydro terms are evolved by a modified RK2-type of step.
  - Implicit terms are handled by backward Euler and Crank-Nicolson steps.
  - Evolves the moments of the radiation energy (time-dependent mass matrix).

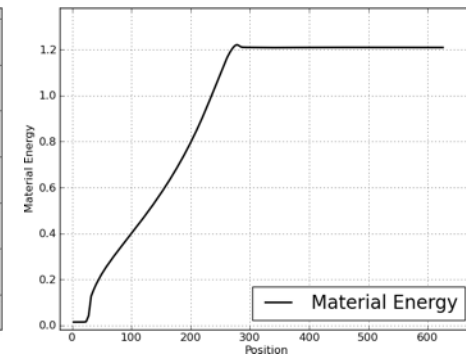
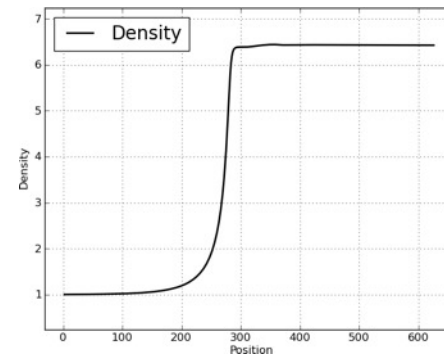
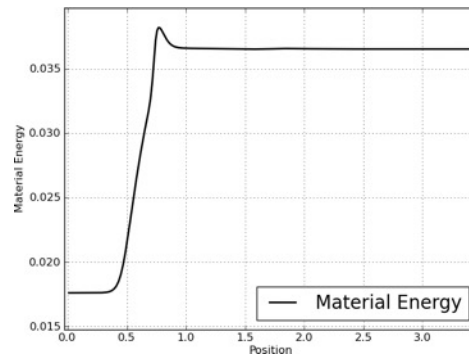
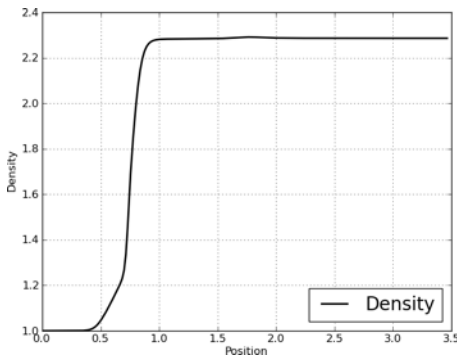
$$\int_{x^{n+1}} E^{n+1} \phi = \int_{x^n} E^n \phi - \Delta t \int_{x^{n+\frac{1}{2}}} \frac{1}{3} E^{n+\frac{1}{2}} \nabla \cdot \bar{v}^{n+\frac{1}{2}} \phi$$
$$+ \frac{\Delta t}{2} \int_{x^n} (-c\sigma^n (E^n - B(T^n)) - \nabla \cdot F^n) \phi + \frac{\Delta t}{2} \int_{x^{n+1}} (-c\sigma^{n+1} (E^{n+1} - B(T^{n+1})) - \nabla \cdot F^{n+1}) \phi$$

# Smooth rad-hydro test / Lowrie shock tube

- Combination of the Taylor-Green vortex and Brunner's smooth diffusion test:
  - Analytic sources keep the manufactured solution constant in time while the mesh evolves.

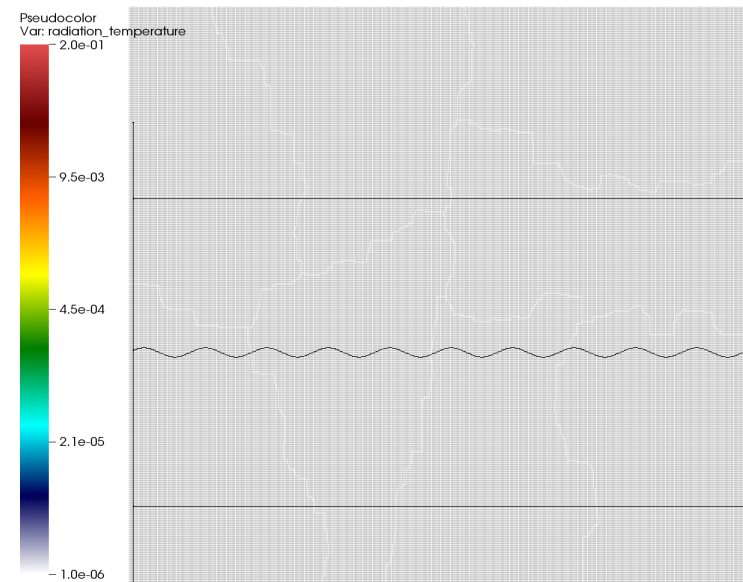
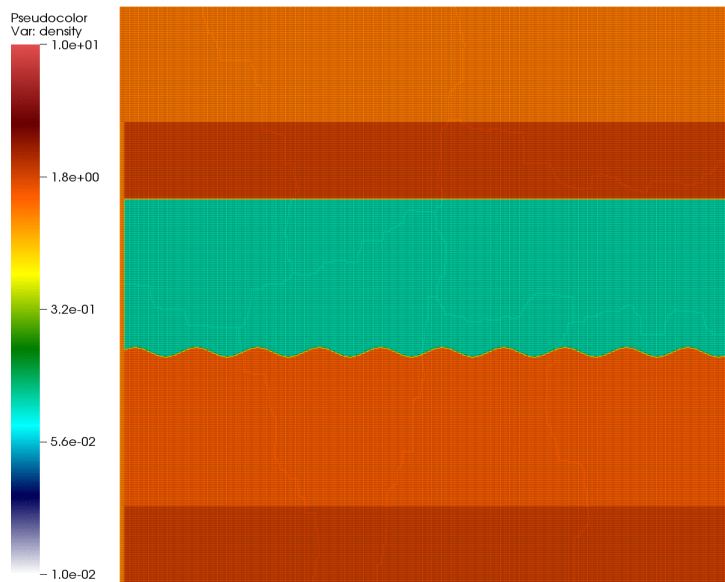


- Lowrie shock tube with temperature-dependent opacities, Mach 2 and 45:



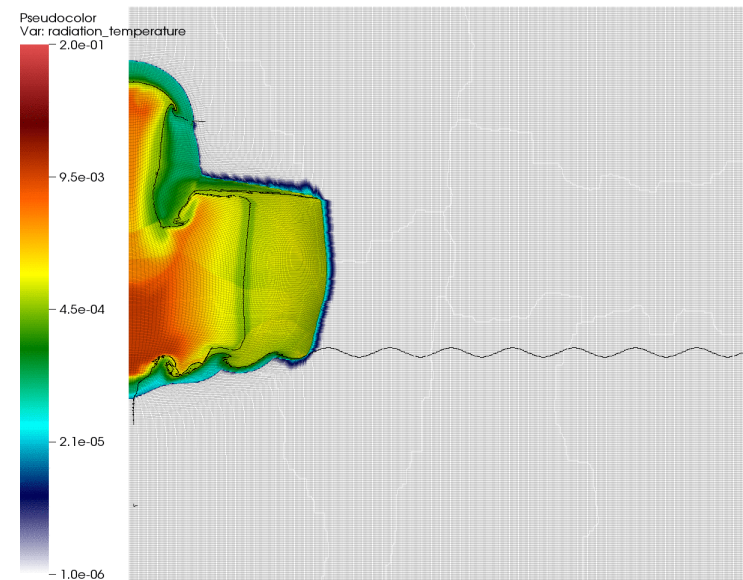
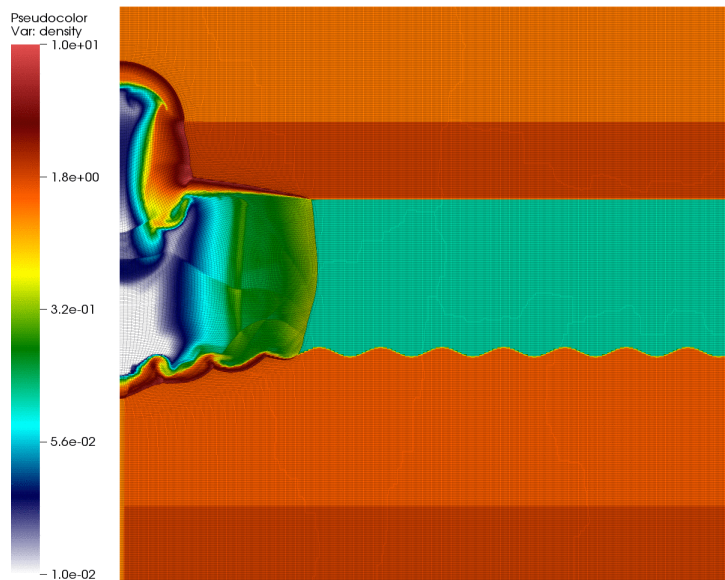
# Extension to full ALE radiation hydrodynamics

- We simply remap  $E$  as a conservative variable (by the FCT advection).
  - There is no need for synchronization with the hydro variables.
  - The radiation flux  $F$  is recomputed from the result of the remap.
- Example: radiating Kelvin-Helmholtz instability:
  - 5 materials (ideal gases),  $Q_2 Q_1$  discretization, constant opacities.



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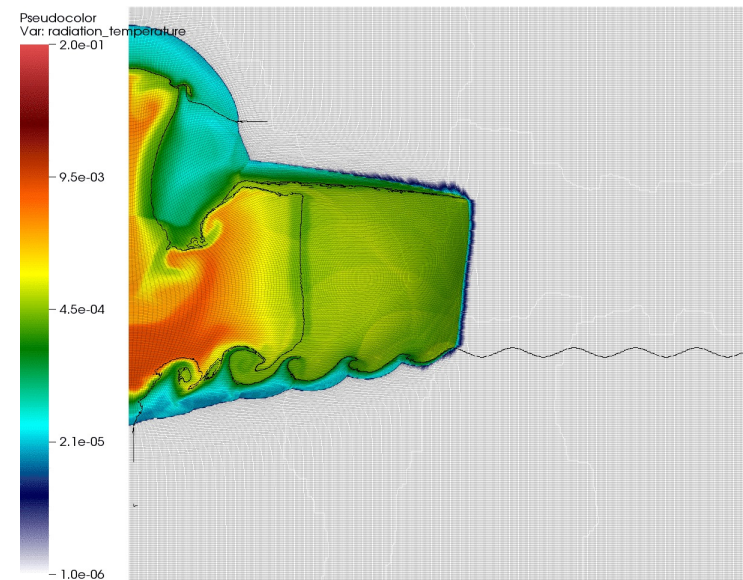
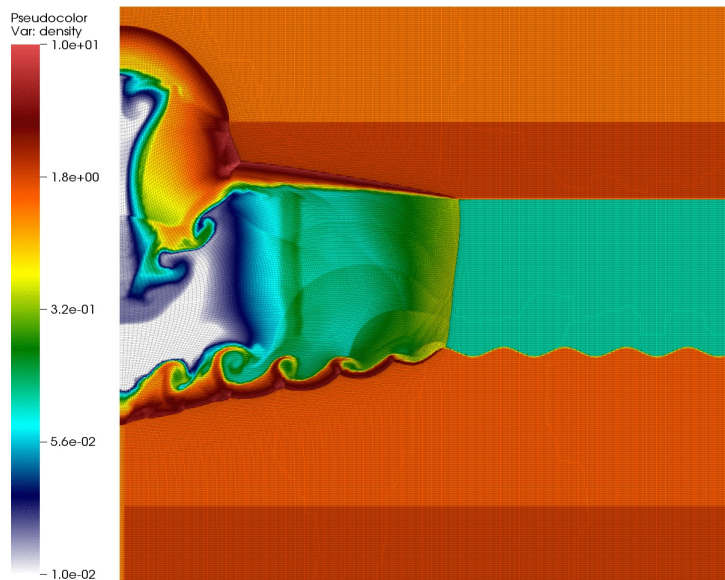
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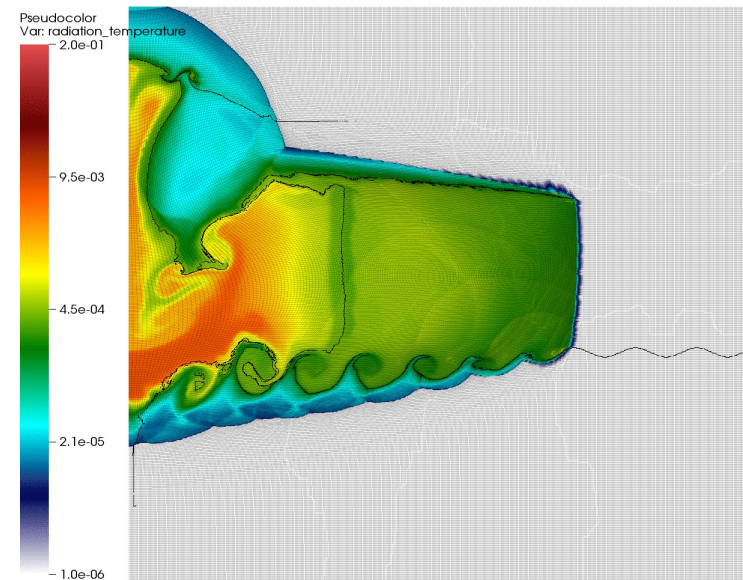
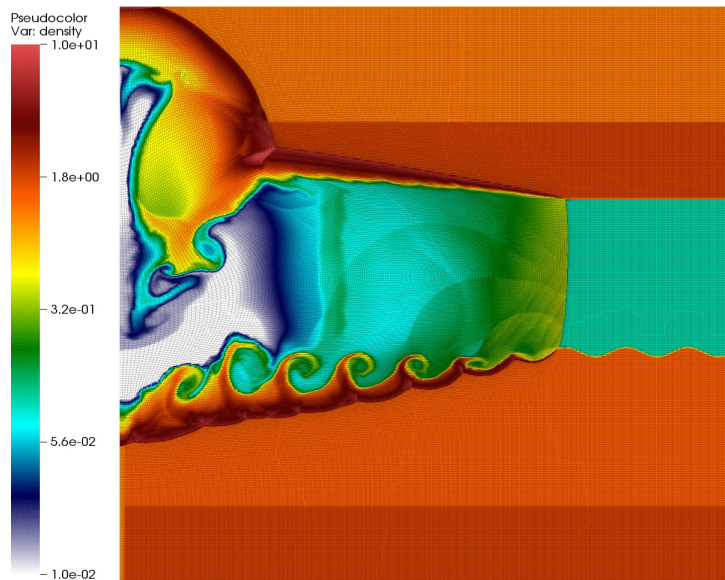
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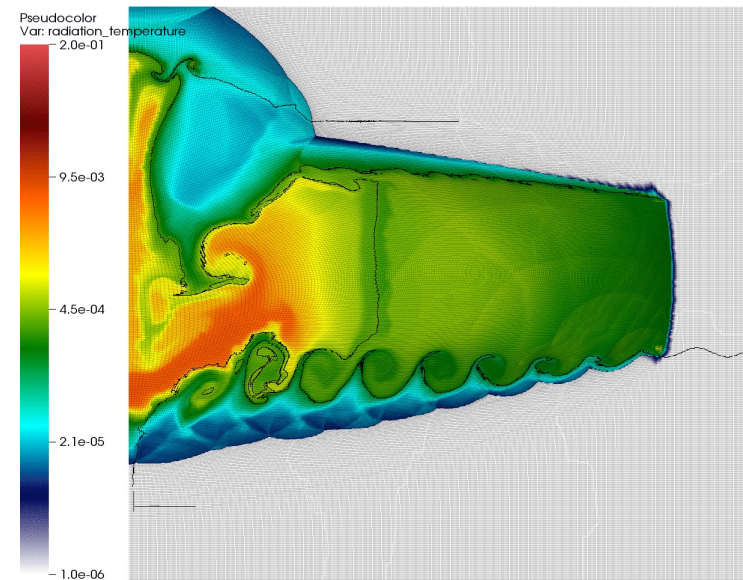
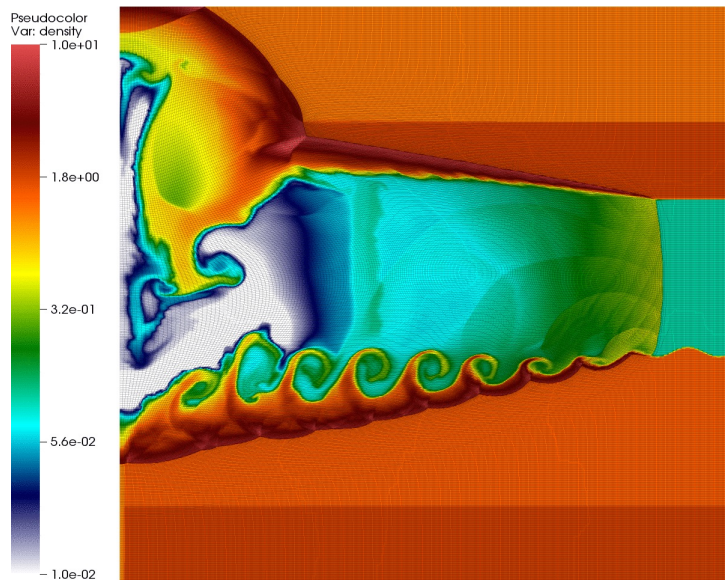
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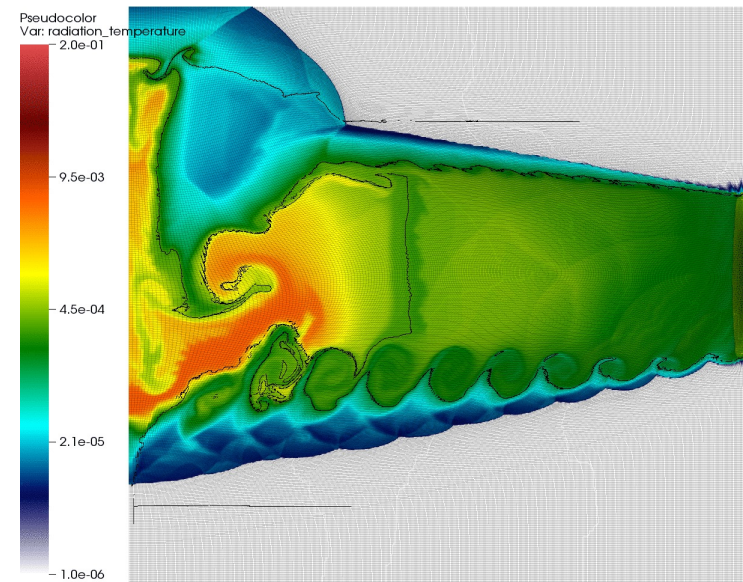
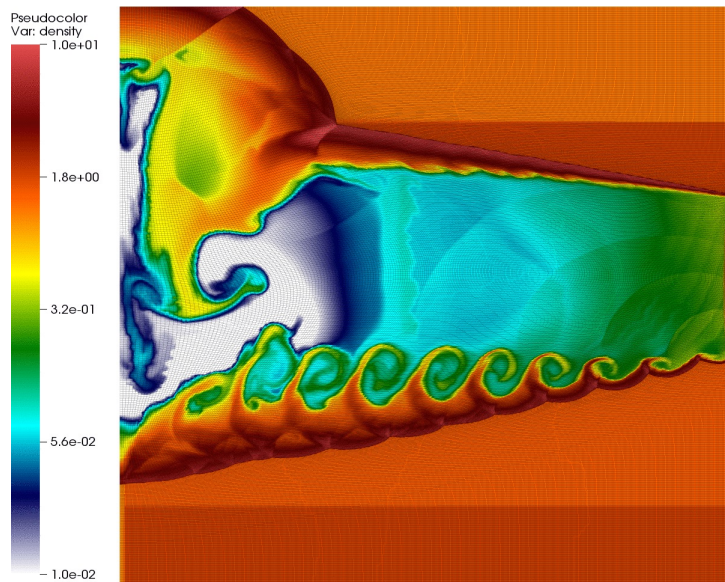
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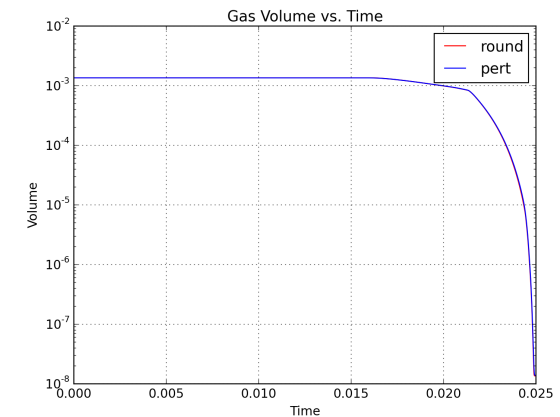
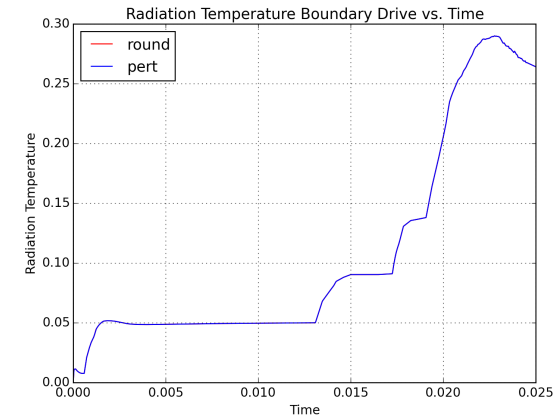
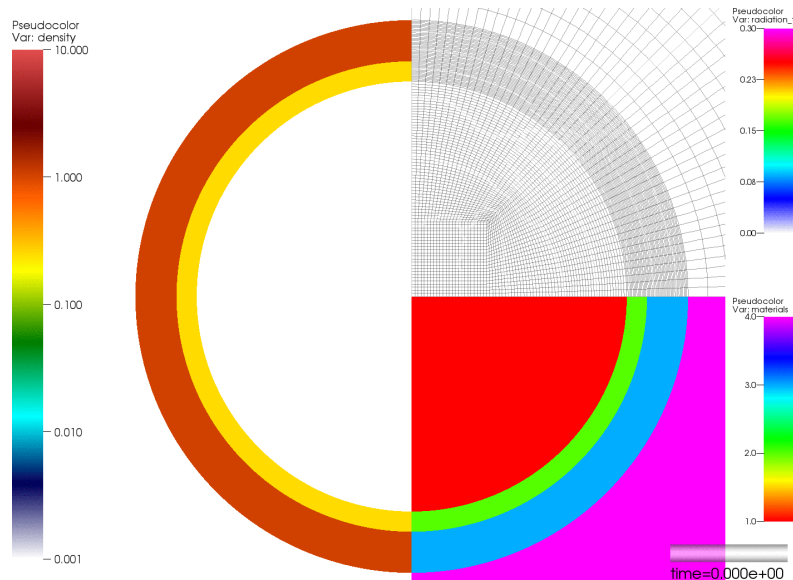
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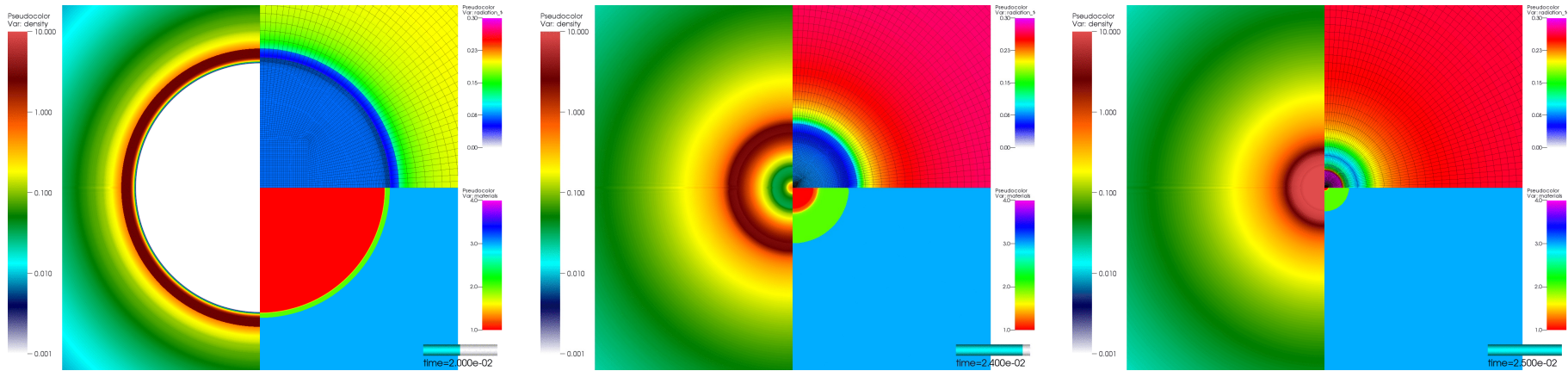
# Single group ICF capsule implosion simulation

- 4 materials, tabular EOS, constant material opacities.
  - Originally proposed by R. Tipton.
- Implosion is achieved by a 4-stage temperature drive.
  - The four shock waves collide to achieve the final implosion.
- Results in  $\approx 40$  times reduction in the DT-gas radius.

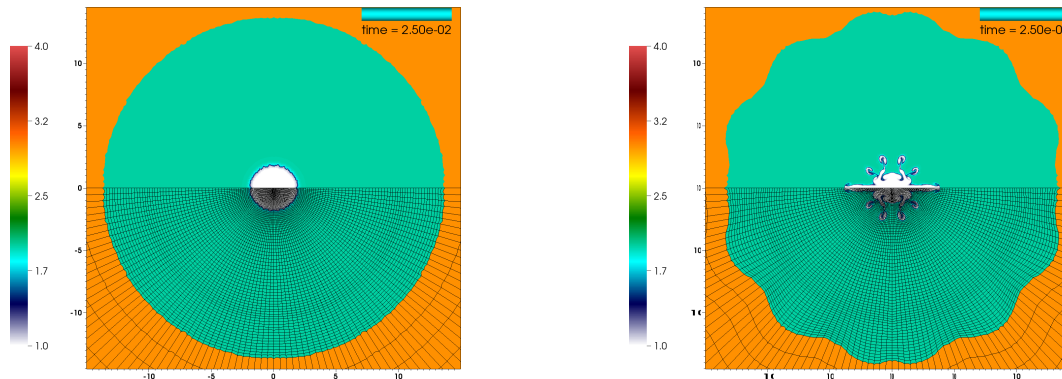


# Single group ICF capsule implosion simulation

- Density, radiation temperature, material positions at times 2 / 2.4 / 2.5.



- Final shape of the gas for round / perturbed initial material interfaces.



# Summary

- We utilize the  $H(\text{div})$  diffusion flux formulation to combine the  $H^1, L_2$  and  $H(\text{div})$  high-order finite element spaces.
- We propose two methods for solving the resulting nonlinear system:
  - #1: Elimination of the energy unknowns,  $H(\text{div})$  linear solve and back-substitution.
  - #2: block Gauss-Seidel iteration (appropriate for multigroup).
- IMEX time discretization combines explicit hydro and implicit radiation diffusion.
- High-order convergence in space and time for smooth problems.
  - Achieved for thick and thin regimes, structured and unstructured meshes.
- The remap of radiation energy does not complicate the remap phase.
- The method is valid for 2Dxy, 2Drz and 3D unstructured curved meshes, general opacity and material models.

